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Michaud, F.; Robichaud, E.;
Intelligent Robots and System, 2002. IEEE/RSJ International Conference on
Volume 3, 30 Sept.-5 Oct. 2002 Page(s):2746 - 2751 vol.3
IEEE CNF
2. **Robot localization using ultrasonic sensors**
Sewan Kim; Younggie Kim;
Intelligent Robots and Systems, 2004. (IROS 2004). Proceedings. 2004
IEEE/RSJ International Conference on
Volume 4, 28 Sept.-2 Oct. 2004 Page(s):3762 - 3766 vol.4
IEEE CNF
3. **Automatic inspection of hazardous materials by mobile robot**
Wilson, J.C.; Berardo, P.A.;
Systems, Man and Cybernetics, 1995. 'Intelligent Systems for the 21st Century'.
IEEE International Conference on
Volume 4, 22-25 Oct. 1995 Page(s):3280 - 3285 vol.4
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Charging stations in the field help provide uninterrupted ... Modularity of charging contacts / bumpers allowing for different **robot** platforms. ... research.cens.ucla.edu/pls/portal/

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